

**Unit- I****Chapter 1 : Introduction****1-1 to 1-31**

Syllabus : Introduction to Artificial Intelligence, Foundations of Artificial Intelligence, History of Artificial Intelligence, State of the Art, Risks and Benefits of AI, Intelligent Agents, Agents and Environments, Good Behavior : Concept of Rationality, Nature of Environments, Structure of Agents.

| | | |
|-------------|---|-------------|
| 1.1 | Introduction to Artificial Intelligence..... | 1-1 |
| 1.2 | Foundations and Mathematical Treatments | 1-1 |
| 1.2.1 | Acting Humanly : The Turing Test Approach..... | 1-1 |
| 1.2.2 | Thinking Humanly : The Cognitive Modelling Approach | 1-2 |
| 1.2.3 | Thinking Rationally : The “Laws of Thought” Approach..... | 1-3 |
| 1.2.4 | Acting Rationally : The Rational Agent Approach..... | 1-3 |
| 1.3 | Categorization of Intelligent Systems | 1-4 |
| 1.4 | Components of AI | 1-4 |
| 1.4.1 | Computational Intelligence vs. Artificial Intelligence..... | 1-6 |
| 1.5 | History of Artificial Intelligence | 1-6 |
| 1.5.1 | Applications of Artificial Intelligence | 1-7 |
| 1.6 | Sub Areasb/ Domains of Artificial Intelligence..... | 1-8 |
| 1.6.1 | Benefits of Artificial Intelligence..... | 1-9 |
| 1.6.2 | Risks of Artificial Intelligence | 1-11 |
| 1.7 | State of the Art..... | 1-11 |
| 1.8 | Intelligent Agents..... | 1-12 |
| 1.8.1 | What is an Agent ? | 1-12 |
| 1.8.2 | Definition of Agent | 1-14 |
| 1.8.3 | Definition of Intelligent Agent..... | 1-15 |
| 1.8.3(A) | Structure of Intelligent Agent..... | 1-16 |
| 1.9 | Rational Agent..... | 1-17 |
| 1.10 | Environments Types and PEAS Properties of Agent..... | 1-18 |
| 1.10.1 | Environments Types | 1-18 |
| 1.10.2 | PEAS Properties of Agent..... | 1-22 |
| 1.11 | Types of Agents..... | 1-24 |



| | | |
|--------|--------------------------------|------|
| 1.11.1 | Simple Reflex Agents..... | 1-24 |
| 1.11.2 | Model-based Reflex Agent | 1-26 |
| 1.11.3 | Goal-based Agent..... | 1-27 |
| 1.11.4 | Utility-based Agent..... | 1-28 |
| 1.11.5 | Learning Agents | 1-29 |

Unit- II**Chapter 2 : Problem-Solving****2-1 to 2-46**

Syllabus : Solving Problems by Searching, Problem-Solving Agents, Example Problems, Search Algorithms, Uninformed Search Strategies, Informed (Heuristic) Search Strategies, Heuristic Functions, Search in Complex Environments, Local Search and Optimization Problems.

| | | |
|------------|---|-------------|
| 2.1 | Solving Problems by Searching..... | 2-1 |
| 2.2 | Formulating Problems | 2-1 |
| 2.2.1 | Components of Problems Formulation..... | 2-2 |
| 2.2.2 | Example of 8-Puzzle Problem | 2-3 |
| 2.2.3 | Example of Missionaries and Cannibals Problem | 2-3 |
| 2.2.4 | Vacuum-Cleaner Problem..... | 2-4 |
| 2.2.5 | Example of Real Time Problems | 2-4 |
| 2.3 | Measuring Performance of Problem Solving Algorithm / Agent | 2-5 |
| 2.4 | Node Representation in Search Tree | 2-5 |
| 2.5 | Uninformed Search Strategies..... | 2-6 |
| 2.5.1 | Depth First Search (DFS)..... | 2-6 |
| 2.5.2 | Breadth First Search (BFS)..... | 2-9 |
| 2.5.3 | Uniform Cost Search (UCS)..... | 2-10 |
| 2.5.4 | Depth Limited Search (DLS) | 2-11 |
| 2.5.5 | Iterative Deepening DFS (IDDFS)..... | 2-12 |
| 2.5.6 | Bidirectional Search | 2-15 |
| 2.6 | Comparing Different Techniques | 2-16 |
| 2.6.1 | Difference between Unidirectional and Bidirectional Search..... | 2-17 |
| 2.6.2 | Difference between BFS and DFS..... | 2-18 |



| | | |
|-------------|--|-------------|
| 2.7 | Informed Search Techniques..... | 2-19 |
| 2.8 | Heuristic Function | 2-19 |
| 2.8.1 | Example of 8-puzzle Problem | 2-20 |
| 2.8.2 | Example of Block World Problem | 2-21 |
| 2.8.3 | Properties of Good Heuristic Function..... | 2-23 |
| 2.9 | Best First Search..... | 2-23 |
| 2.9.1 | Greedy Best First Search | 2-25 |
| 2.10 | A* Search..... | 2-26 |
| 2.10.1 | Concept | 2-26 |
| 2.10.2 | Implementation..... | 2-27 |
| 2.10.3 | Algorithm (A*) | 2-27 |
| 2.10.4 | Behaviour of A* Algorithm | 2-28 |
| 2.10.5 | Admissibility of A* | 2-29 |
| 2.10.6 | Monotonicity..... | 2-30 |
| 2.10.7 | Properties of A* | 2-31 |
| 2.10.8 | Example : 8 Puzzle Problem using A* Algorithm..... | 2-31 |
| 2.10.9 | Comparison among Best First Search, A* Search and Greedy Best First Search | 2-33 |
| 2.11 | Local Search Algorithms and Optimization Problems..... | 2-35 |
| 2.11.1 | Hill Climbing..... | 2-35 |
| 2.11.1(A) | Simple Hill Climbing | 2-36 |
| 2.11.1(B) | Steepest Ascent Hill Climbing..... | 2-36 |
| 2.11.1(C) | Limitations of Hill Climbing..... | 2-37 |
| 2.11.1(D) | Solutions on Problems in Hill Climbing..... | 2-38 |
| 2.11.2 | Simulated Annealing..... | 2-39 |
| 2.11.2(A) | Comparing Simulated Annealing with Hill Climbing..... | 2-40 |
| 2.11.3 | Local Beam Search..... | 2-40 |
| 2.11.4 | Genetic Algorithms..... | 2-43 |
| 2.11.4(A) | Terminologies of GA | 2-43 |
| 2.11.4(B) | Genetic Operators | 2-44 |
| 2.11.4(C) | The Basic Genetic Algorithm..... | 2-45 |
| 2.11.4(D) | Example of Genetic Algorithm..... | 2-45 |

**Unit- III****Chapter 3 : Adversarial Search and Games****3-1 to 3-26**

Syllabus : Game Theory, Optimal Decisions in Games, Heuristic Alpha - Beta Tree Search, Monte Carlo Tree Search, Stochastic Games, Partially Observable Games, Limitations of Game Search Algorithms, Constraint Satisfaction Problems (CSP), Constraint Propagation : Inference in CSPs, Backtracking Search for CSPs.

| | | |
|------------|---|-------------|
| 3.1 | Adversarial Search | 3-1 |
| 3.1.1 | Environment Types | 3-1 |
| 3.1.2 | AI Game - Features..... | 3-2 |
| 3.1.2(A) | Zero Sum Game..... | 3-2 |
| 3.1.2(B) | Non-Zero Sum Game | 3-3 |
| 3.2 | Relevant Aspects of AI Game..... | 3-3 |
| 3.3 | Game Playing | 3-4 |
| 3.3.1 | Type of Game Strategies | 3-4 |
| 3.3.2 | Type of Games..... | 3-5 |
| 3.3.2(A) | Chess | 3-6 |
| 3.3.2(B) | Checkers | 3-6 |
| 3.3.3 | What is Game Tree?..... | 3-7 |
| 3.4 | Minimax Algorithm..... | 3-9 |
| 3.4.1 | Minimax Algorithm..... | 3-9 |
| 3.4.2 | Properties of Minimax Algorithm..... | 3-12 |
| 3.5 | Alpha Beta Pruning | 3-12 |
| 3.5.1 | Example of α - β Pruning | 3-14 |
| 3.5.2 | Properties of α - β | 3-17 |
| 3.6 | Constraint Satisfaction Problem..... | 3-17 |
| 3.6.1 | Examples of CSPs..... | 3-18 |
| 3.6.2 | Varieties of CSPs..... | 3-19 |
| 3.6.3 | Varieties of Constraints..... | 3-19 |
| 3.6.4 | Backtracking in CSPs..... | 3-19 |
| 3.6.5 | Improving Backtracking Efficiency..... | 3-20 |
| 3.7 | Crypto-Arithmetic Problem..... | 3-23 |

**Unit - IV****Chapter 4 : Knowledge** 4-1 to 4-24

Syllabus : Logical Agents, Knowledge-based Agents, The WUMPUS World, Logic, Propositional Logic : A Very Simple Logic, Propositional Theorem Proving, Effective Propositional Model Checking, Agents Based on Propositional Logic, First-Order Logic, Representation Revisited, Syntax and Semantics of First-Order Logic, Using First-Order Logic, Knowledge Engineering in First-Order Logic.

| | |
|---|-------------|
| 4.1 A Knowledge Based (KB) Agent | 4-1 |
| 4.1.1 Architecture of a KB Agent | 4-2 |
| 4.2 The WUMPUS World Environment | 4-3 |
| 4.2.1 Description of the WUMPUS World | 4-5 |
| 4.2.2 PEAS Properties of WUMPUS World | 4-5 |
| 4.2.3 Exploring a WUMPUS World | 4-6 |
| 4.3 Logic | 4-9 |
| 4.3.1 Role of Reasoning in AI | 4-10 |
| 4.4 Representation of Knowledge using Rules | 4-10 |
| 4.4.1 Ontology | 4-13 |
| 4.5 Propositional Logic (PL) | 4-13 |
| 4.5.1 Syntax | 4-13 |
| 4.5.2 Semantics | 4-14 |
| 4.5.3 What is Propositional Logic ? | 4-15 |
| 4.5.4 PL Sentence - Example | 4-15 |
| 4.5.5 Inference Rules | 4-16 |
| 4.5.6 Horn Clause | 4-17 |
| 4.5.7 Propositional Theorem Proving | 4-18 |
| 4.5.8 Advantages of Propositional Logic | 4-19 |
| 4.5.9 Disadvantages of Propositional Logic | 4-19 |
| 4.6 First Order Predicate Logic | 4-19 |
| 4.6.1 Syntactic Elements, Semantic and Syntax | 4-19 |
| 4.7 Knowledge Engineering in First-Order Logic | 4-21 |

**Unit- V****Chapter 5 : Reasoning****5-1 to 5-26**

Syllabus : Inference in First-Order Logic, Propositional vs. First-Order Inference, Unification and First-Order Inference, Forward Chaining, Backward Chaining, Resolution, Knowledge Representation, Ontological Engineering, Categories and Objects, Events, Mental Objects and Modal Logic, Reasoning Systems for Categories, Reasoning with Default Information

| | | |
|-------------|--|-------------|
| 5.1 | Inference in First-Order Logic (FOL)..... | 5-1 |
| 5.1.1 | Forward Chaining..... | 5-1 |
| 5.1.2 | Backward Chaining..... | 5-3 |
| 5.1.3 | Difference between Forward Chaining and Backward Chaining..... | 5-4 |
| 5.2 | Comparison between Propositional Logic and First Order Logic..... | 5-5 |
| 5.3 | Knowledge Engineering Process | 5-6 |
| 5.4 | Unification and Lifting..... | 5-7 |
| 5.4.1 | Unification | 5-7 |
| 5.4.2 | Lifting..... | 5-8 |
| 5.5 | Resolution..... | 5-9 |
| 5.5.1 | The Resolution Procedure | 5-10 |
| 5.5.2 | Conversion from FOL Clausal Normal Form (CNF)..... | 5-10 |
| 5.5.3 | Facts Representation | 5-10 |
| 5.6 | Ontological Engineering | 5-18 |
| 5.7 | Categories and Objects..... | 5-19 |
| 5.8 | Events, Mental Events and Mental Objects..... | 5-20 |
| 5.8.1 | Events and Mental Objects | 5-21 |
| 5.8.2 | Modal Logic | 5-21 |
| 5.9 | Reasoning Systems for Categories | 5-22 |
| 5.9.1 | Semantic Networks..... | 5-22 |
| 5.9.2 | Advantages of Semantic Nets | 5-23 |
| 5.9.3 | Disadvantage of Semantic Nets | 5-24 |
| 5.10 | Reasoning with Default Information..... | 5-24 |
| 5.11 | The Internet Shopping World..... | 5-24 |

**Unit - VI****Chapter 6 : Planning****6-1 to 6-31**

Syllabus : Automated Planning, Classical Planning, Algorithms for Classical Planning, Heuristics for Planning, Hierarchical Planning, Planning and Acting in Nondeterministic Domains, Time, Schedules, and Resources, Analysis of Planning Approaches, Limits of AI, Ethics of AI, Future of AI, AI Components, AI Architectures.

| | | |
|-------------|---|-------------|
| 6.1 | Introduction to Automated Planning..... | 6-1 |
| 6.1.1 | Simple Planning Agent | 6-2 |
| 6.2 | Classical Planning | 6-2 |
| 6.2.1 | Problem Solving and Planning..... | 6-3 |
| 6.2.2 | Goal of Planning | 6-4 |
| 6.2.3 | Algorithms for Classical Planning | 6-5 |
| 6.3 | Planning Graphs | 6-5 |
| 6.4 | Planning as State-Space Search..... | 6-7 |
| 6.4.1 | Example of State Space Search | 6-8 |
| 6.4.2 | Classification of Planning with State Space Search..... | 6-10 |
| 6.5 | Progression Planners | 6-10 |
| 6.6 | Regression Planners | 6-11 |
| 6.6.1 | Heuristics for Planning..... | 6-12 |
| 6.7 | Total Order Planning (TOP) | 6-13 |
| 6.8 | Partial Order Planning..... | 6-13 |
| 6.8.1 | POP as a Search Problem..... | 6-14 |
| 6.8.2 | Consistent Plan is a Solution for POP Problem..... | 6-15 |
| 6.9 | Hierarchical Planning..... | 6-15 |
| 6.9.1 | POP One Level Planner..... | 6-16 |
| 6.9.2 | Hierarchy of Actions..... | 6-17 |
| 6.9.3 | Planner | 6-17 |
| 6.10 | Planning Languages | 6-19 |
| 6.10.1 | Example of Block World Puzzle..... | 6-19 |
| 6.10.2 | Example of the Spare Tire Problem | 6-22 |
| 6.11 | Planning and Acting in Nondeterministic Domains..... | 6-22 |
| 6.12 | Multi-Agent Planning..... | 6-23 |



| | |
|---|-------------|
| 6.13 Conditional Planning | 6-24 |
| 6.14 Time, Schedule and Recources..... | 6-25 |
| 6.14.1 Job Shop Scheduling Problem | 6-25 |
| 6.15 Analysis of Planning Approaches | 6-26 |
| 6.15.1 Limits of AI | 6-27 |
| 6.15.2 Ethics of AI..... | 6-27 |
| 6.15.3 Future of AI | 6-28 |
| 6.16 AI Components | 6-29 |
| 6.16.1 AI Architectures | 6-31 |
